Quick MarkDown Reference

Beamer presentation with Pandoc

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This presentation

Available at

- `gitlab.laas.fr/gsaurel/talks : howto.md`
- `homepages.laas.fr/gsaurel/talks/howto.pdf`

Under License

Table of contents

First Part

Slide title

How-to Slides

Formating: *em* **bold** `mono` ~~strikethrough~~ text$_{\text{subscript}}^{\text{superscript}}$

{Un,}ordered Lists, pause

- eggs
- butter
- ham

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1. Thing
2. Do
3. Words
4. You

Code

```python
#!/usr/bin/env python3
from math import pi as π

class Circle:
    """Define a circle from its radius."""
    def __init__(self, r):
        # such maths, very difficult, wow
        if r < 0:
            raise AttributeError('wrong radius')
        self.P = 2 * π * r
        self.S = π * r ** 2
```

Second Part

Maths

$$\vec{\nabla} \cdot \vec{\mathcal{E}} = \frac{\rho}{\epsilon_0}$$

$$\vec{\nabla} \times \vec{\mathcal{E}} = -\frac{\partial \vec{\mathcal{B}}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{\mathcal{B}} = 0$$

$$\vec{\nabla} \times \vec{\mathcal{B}} = \mu_0 \vec{\mathcal{J}} + \epsilon_0 \frac{\partial \vec{\mathcal{E}}}{\partial t}$$

Tables

Right	Left	Default	Center
12	12	12	12
123	123	123	123
1	1	**1**	~~1~~

Images

Figure 1: Doc

Citations

Look ! The trees... They're moving !

— Saurel, Taïx, and Laumond (2016)

References

Saurel, Guilhem, Michel Taïx, and Jean-Paul Laumond. 2016. "transHumUs: A poetic experience in mobile robotics." In *IEEE International Conference on Robotics and Automation (ICRA)*, 2908–14. Stockholm, Sweden. https://doi.org/10.1109/ICRA.2016.7487455.